

FIG. 1

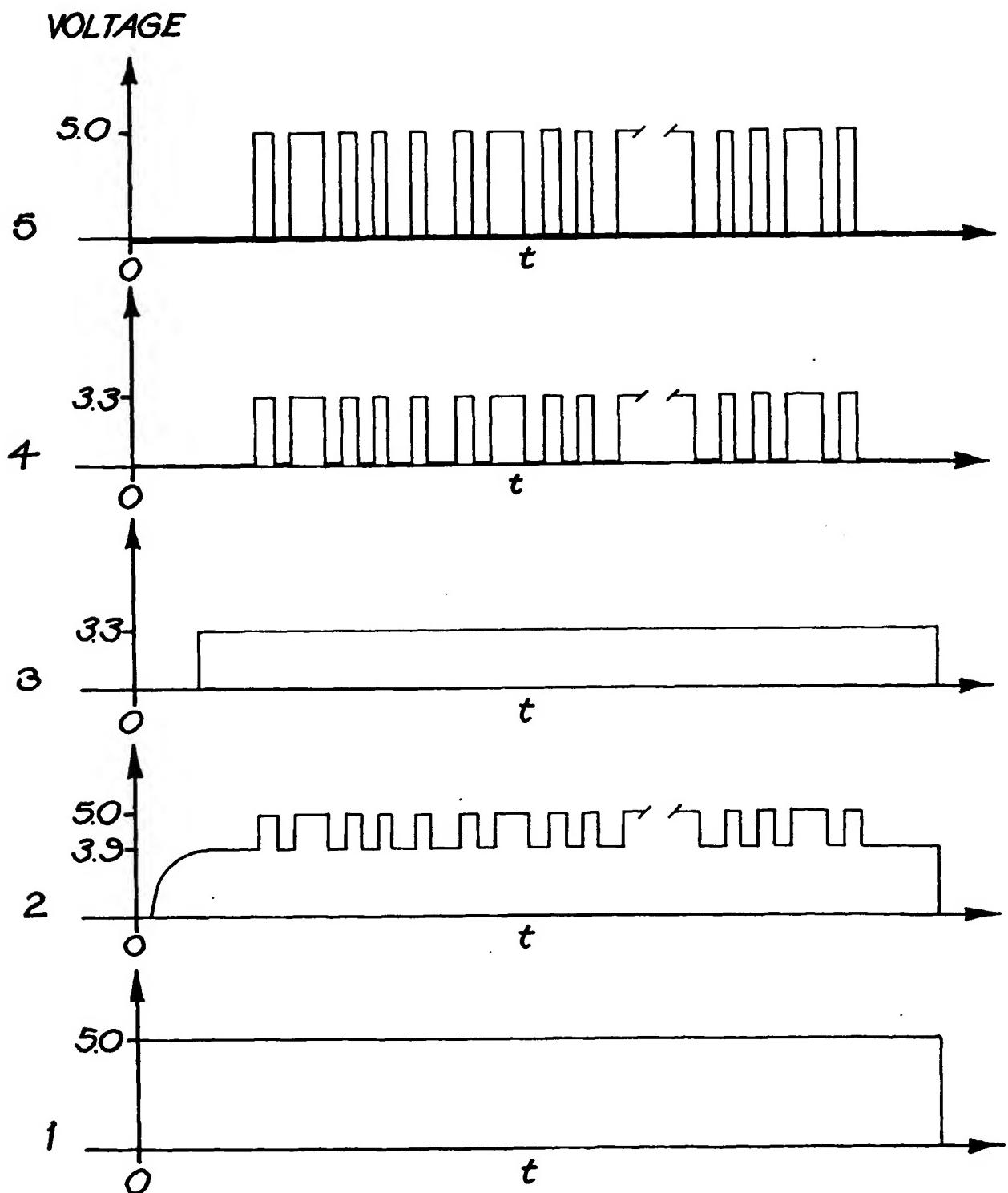


FIG. 2

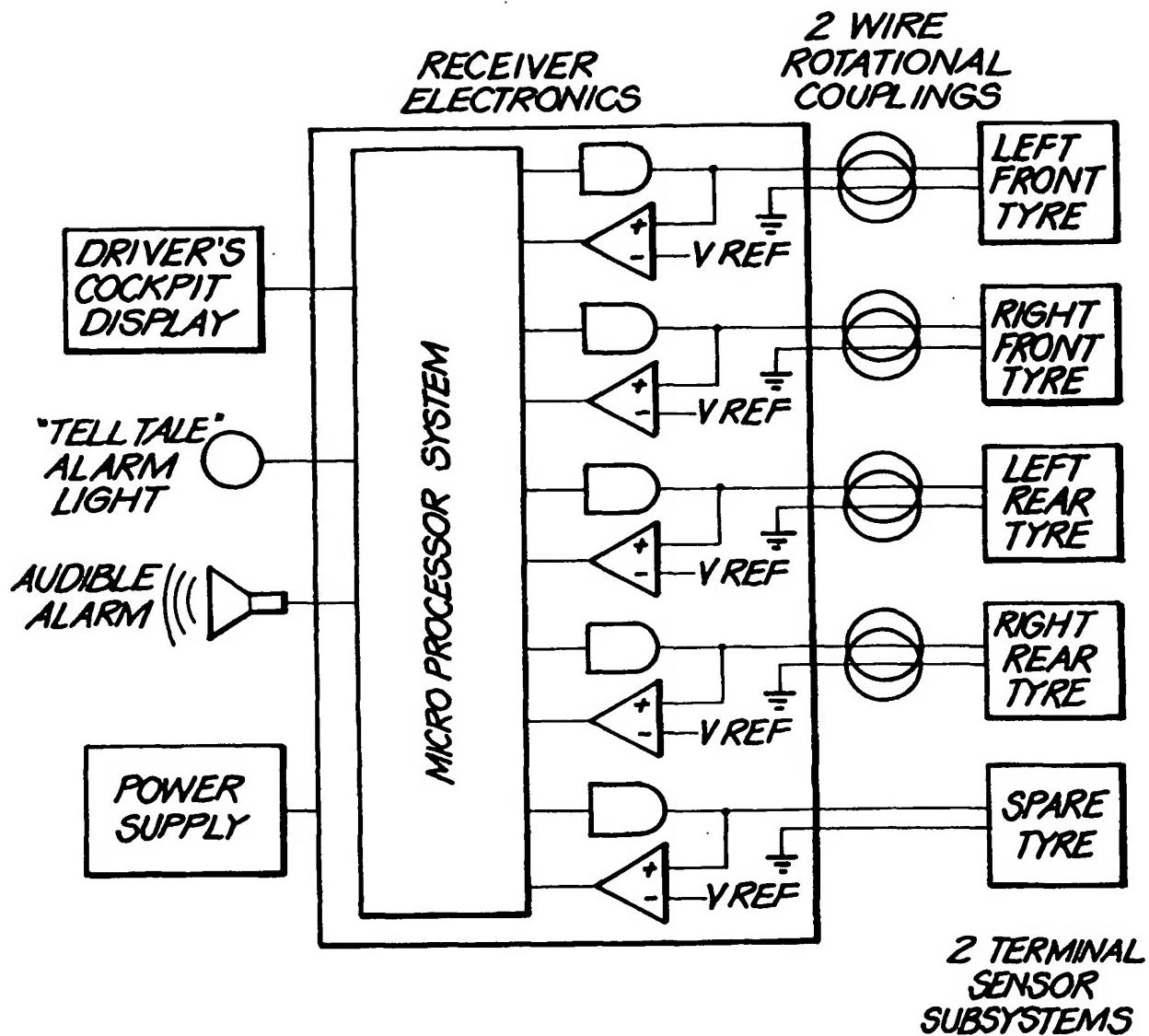
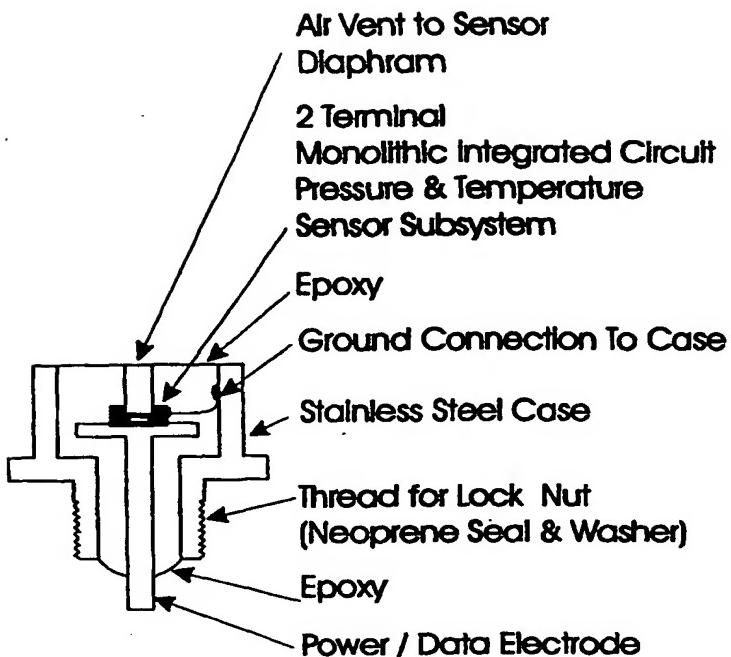
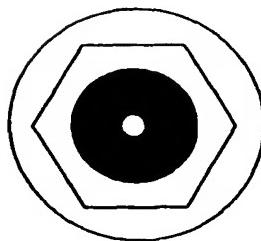
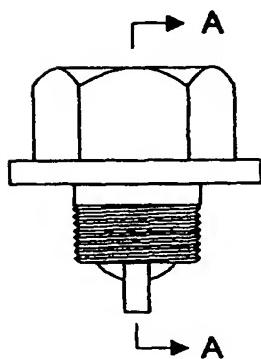
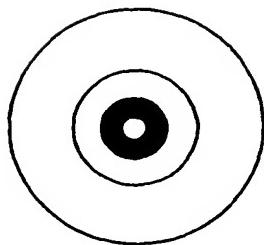


FIG. 3



Section "AA"

2 Terminal Sensor Packaging

Fig. 4

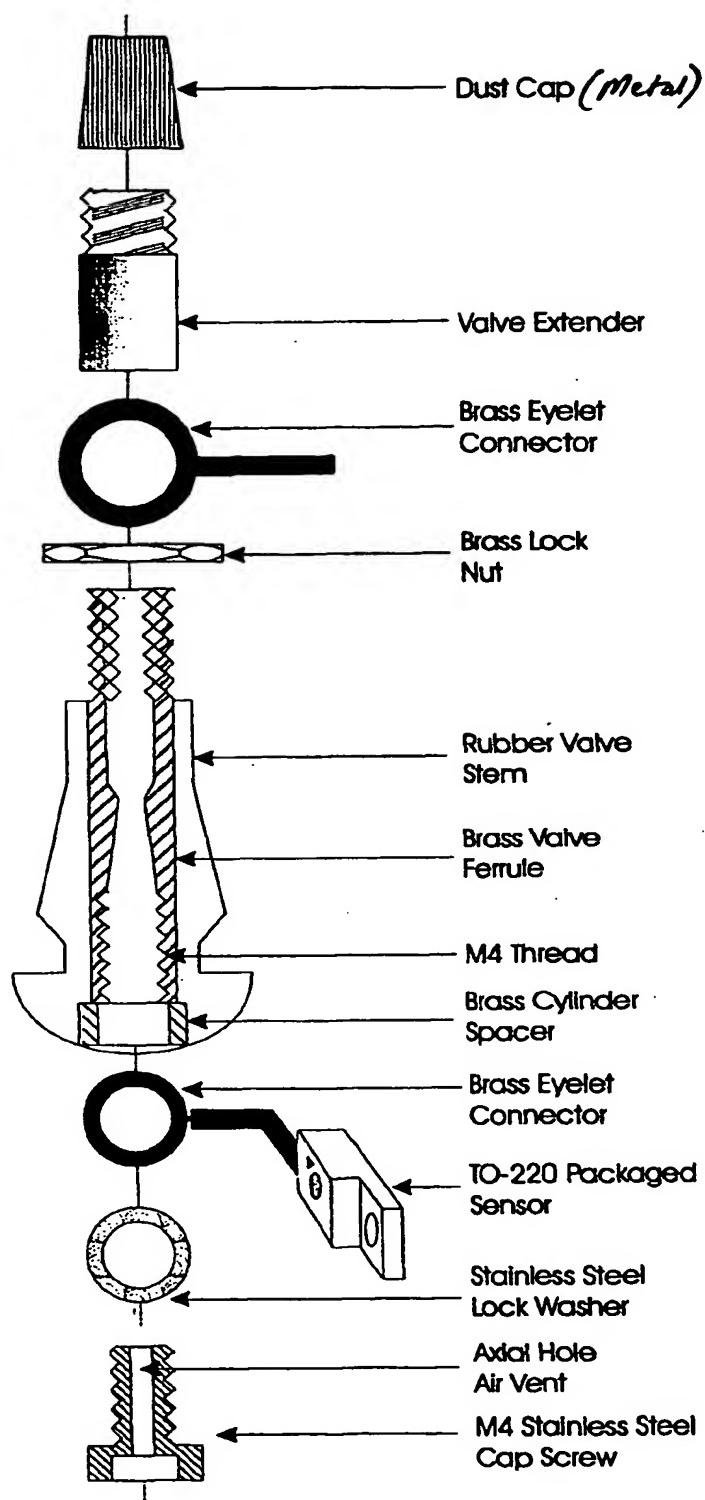
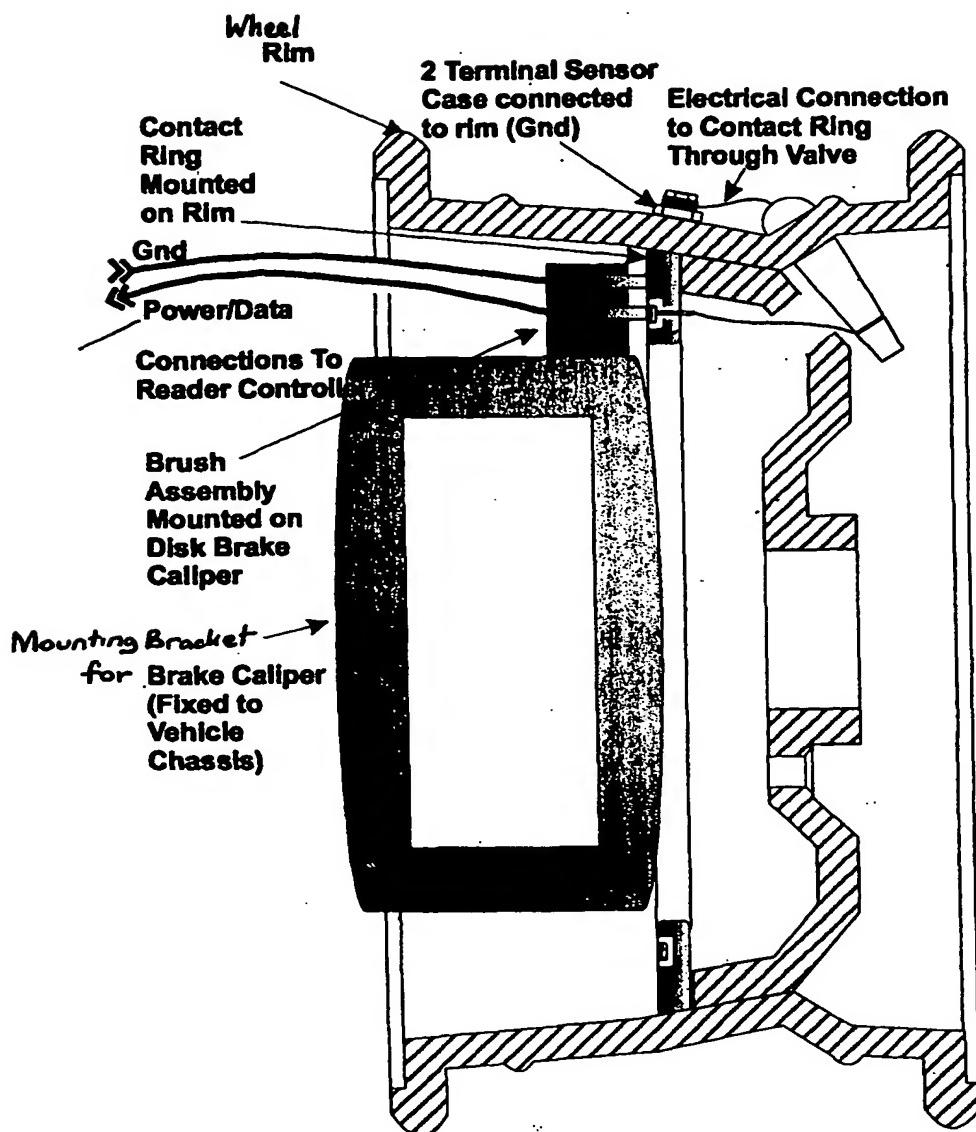
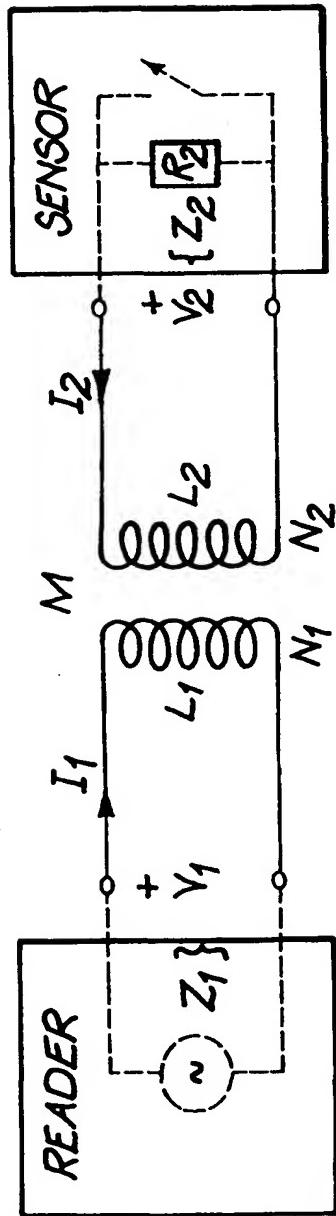


Fig. 5 Tyre Valve Insulated Electrode
Used To Connect Sensor To
External Face Of Wheel Rim

Fig. 6

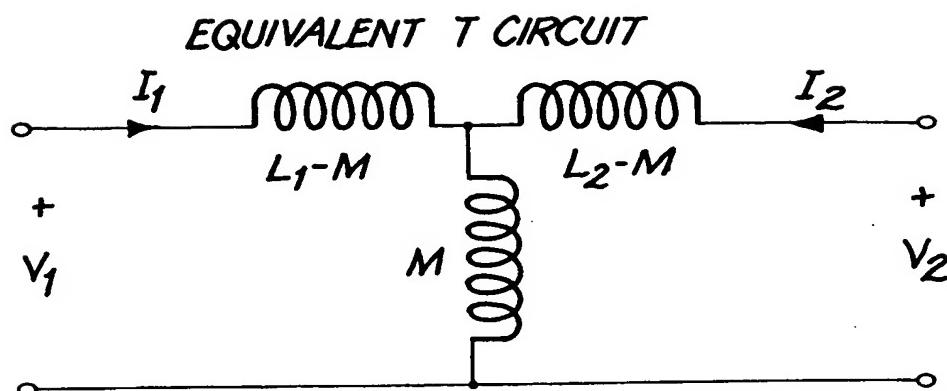
**System Implementation showing
TPMS Enabled Wheel Rim and
TPMS Enabled Disk Brake Caliper**

INDUCTIVELY COUPLED CIRCUIT



$$\begin{aligned}
 &V = Nd\phi/dt = d\lambda/dt = L \frac{dI}{dt} \\
 &\text{FLUX } \phi = \Phi m \sin 2\pi ft \\
 &V_{RMS} = 4.44 N f \Phi m \\
 &V_2 = (N_2 / N_1) V_1 \\
 &I_2 = (V_2 / R_1) \\
 &\text{THE COMPONENT OF PRIMARY CURRENT DUE TO LOAD IS} \\
 &I'_1 = (N_2 / N_1) I_2
 \end{aligned}$$

FIG. 7



FOR SINUSOIDS, VOLTAGE V_{12} COUPLED INTO THE INPUT BY A CURRENT I_2 IS $V_{12} = j\omega M_{12} I_2$

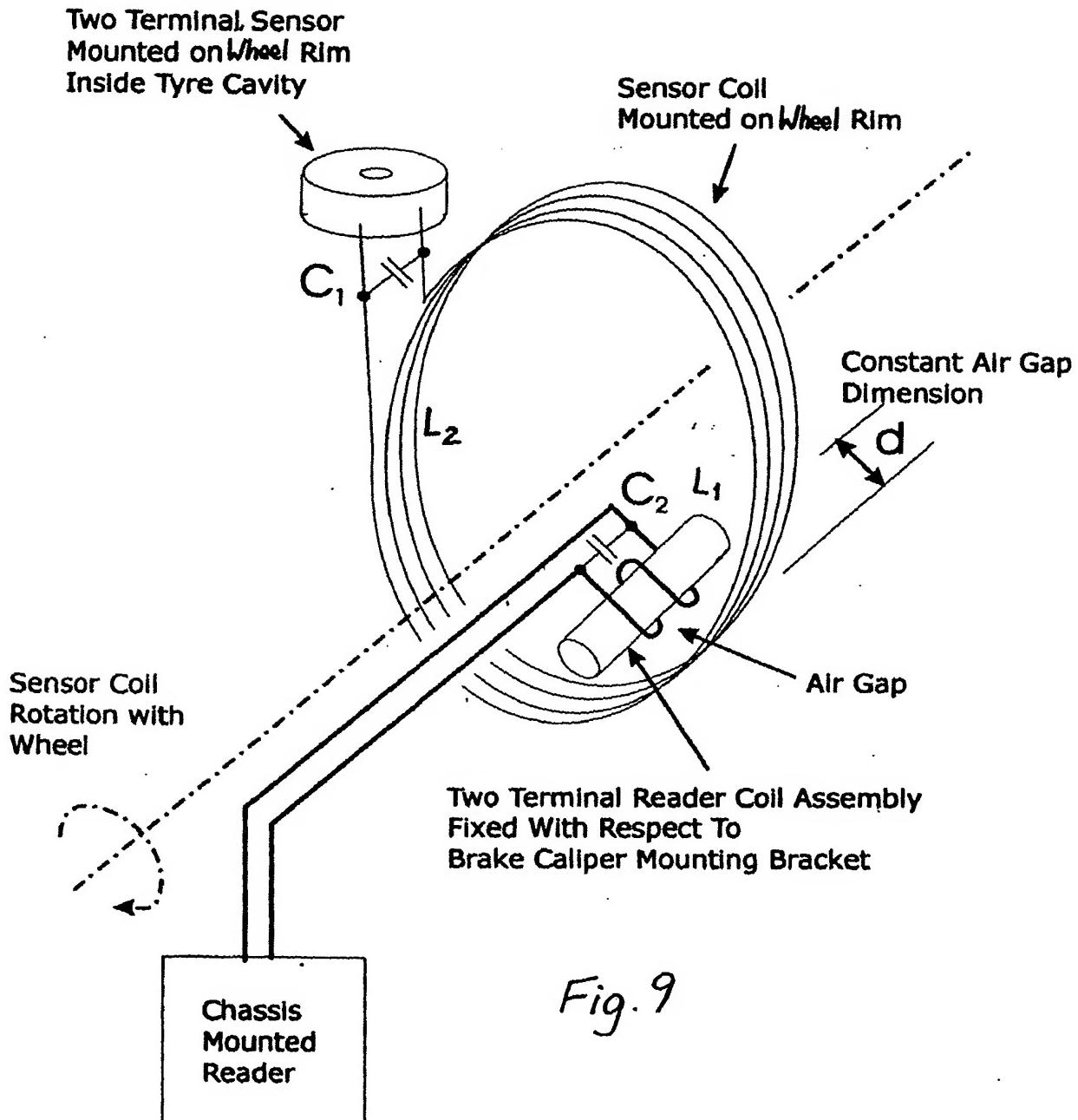
WHERE $Z_{12} = j\omega M_{12}$ = MUTUAL IMPEDANCE

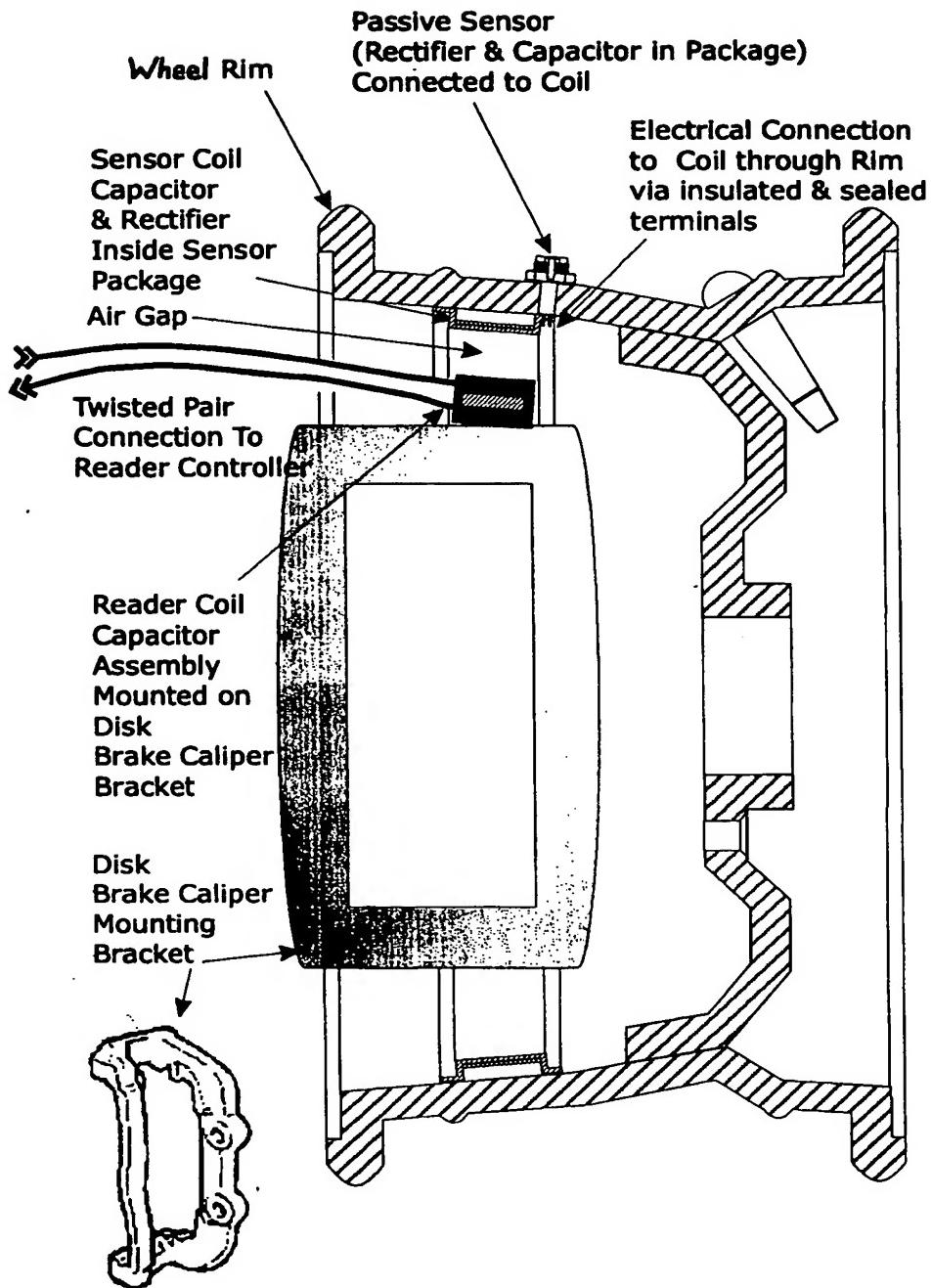
IF $Z_{12} = Z_{21}$ OR $M_{12} = M_{21} = M$ USING RECIPROCITY FOR A BILATERAL NETWORK,

THEN $V_1 = j\omega L_1 I_1 + j\omega M I_2 = Z_{11} I_1 + Z_{12} I_2$

AND $V_2 = j\omega M I_1 + j\omega L_2 I_2 = Z_{21} I_1 + Z_{22} I_2$

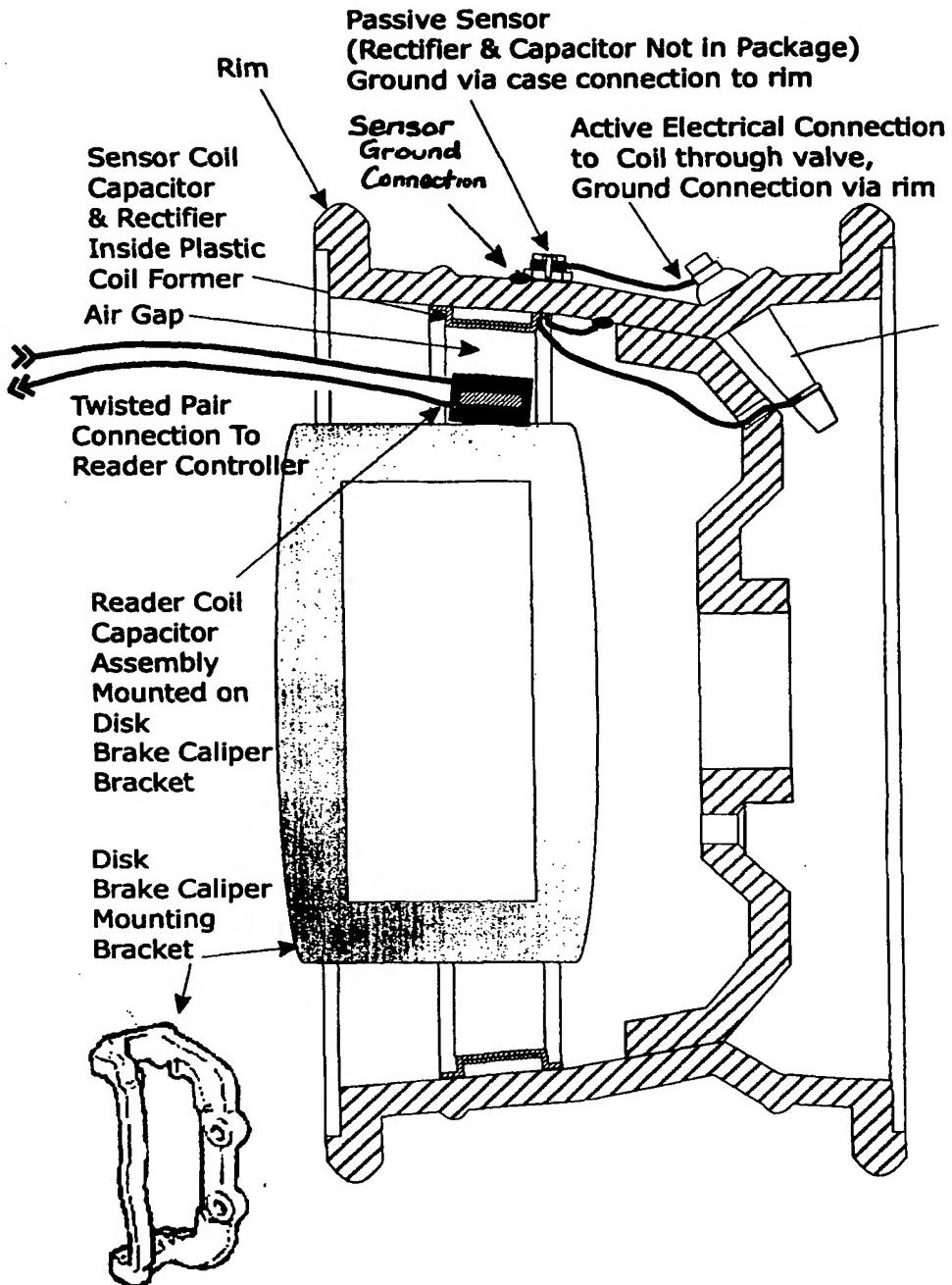
FIG. 8





**Non Contact System Showing
TPMS Enabled Steel Wheel Rim and
TPMS Enabled Disk Brake Caliper
Mounting Bracket**

Fig. 10



**Non Contact System Showing
TPMS Enabled Steel Wheel Rim and
TPMS Enabled Disk Brake Caliper
Mounting Bracket**

Fig. 11

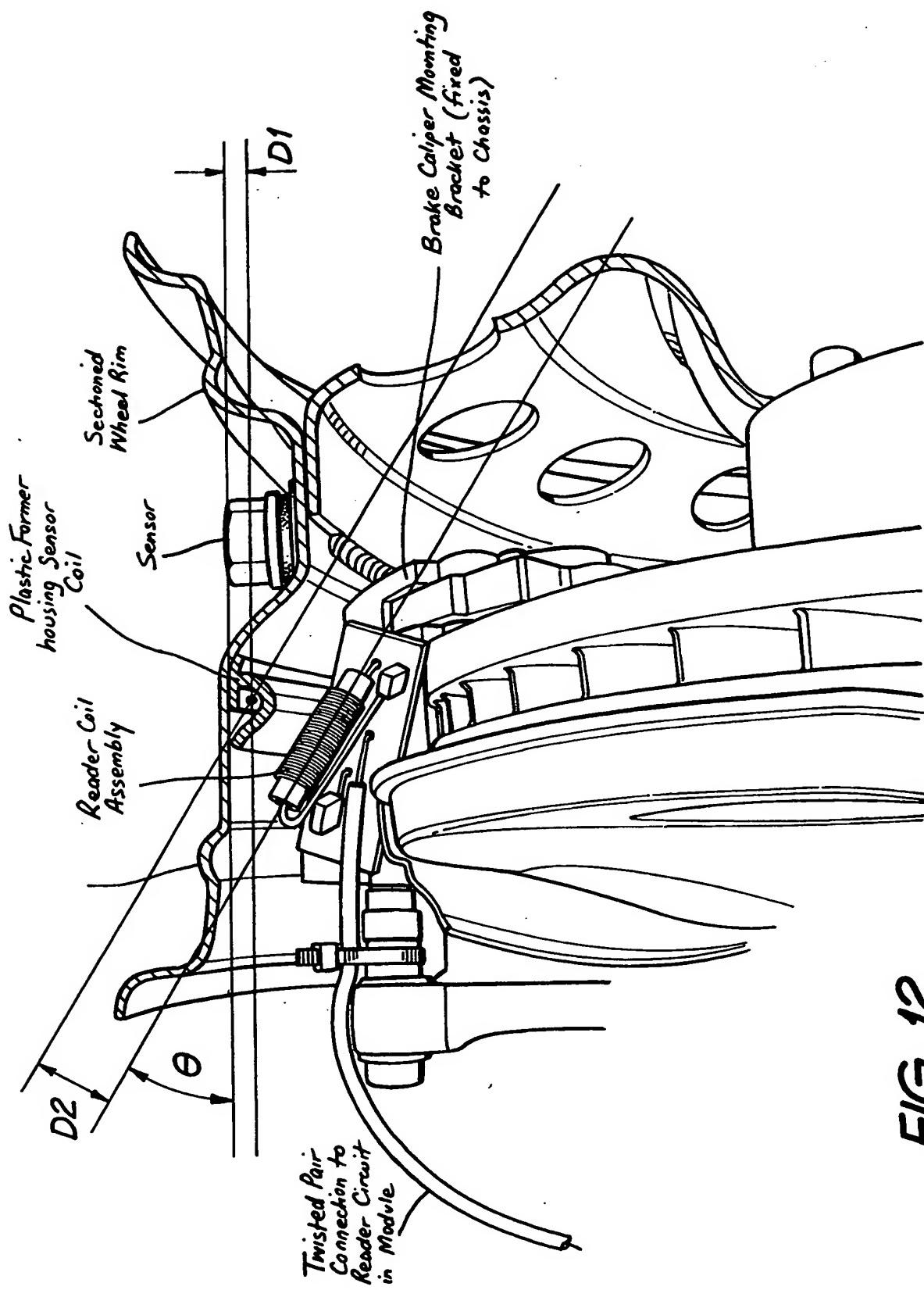


FIG. 12

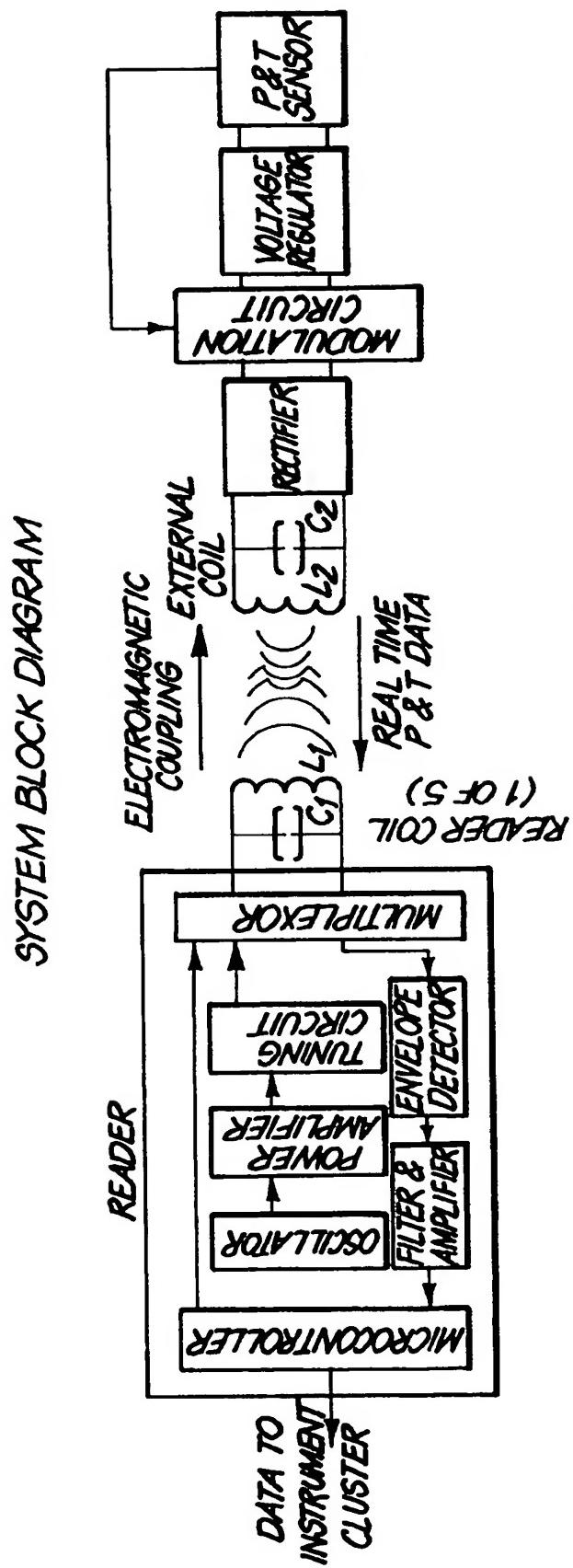


FIG. 13

EXTERNAL COIL & CAPACITOR-
ALL OTHER COMPONENTS IN SENSOR PACKAGE

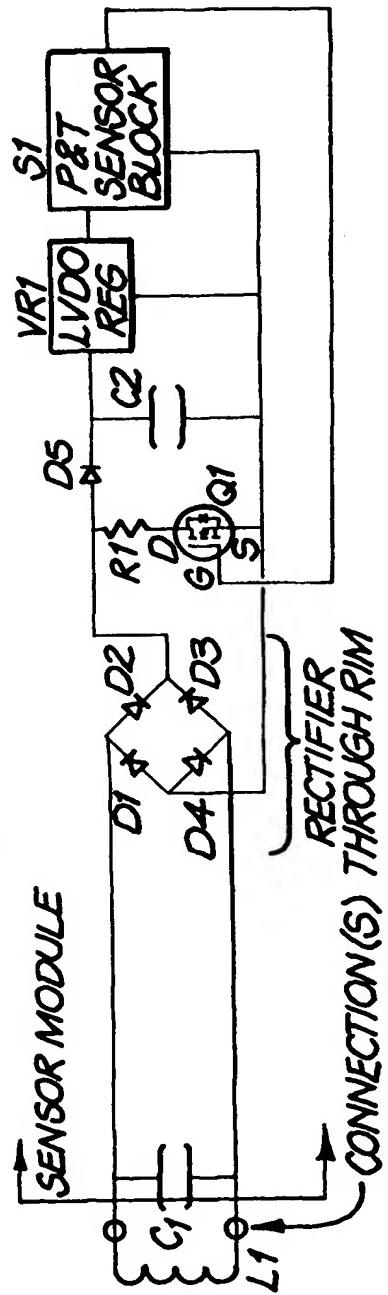


FIG. 14

EXTERNAL COIL, CAPACITOR & BRIDGE RECTIFIER

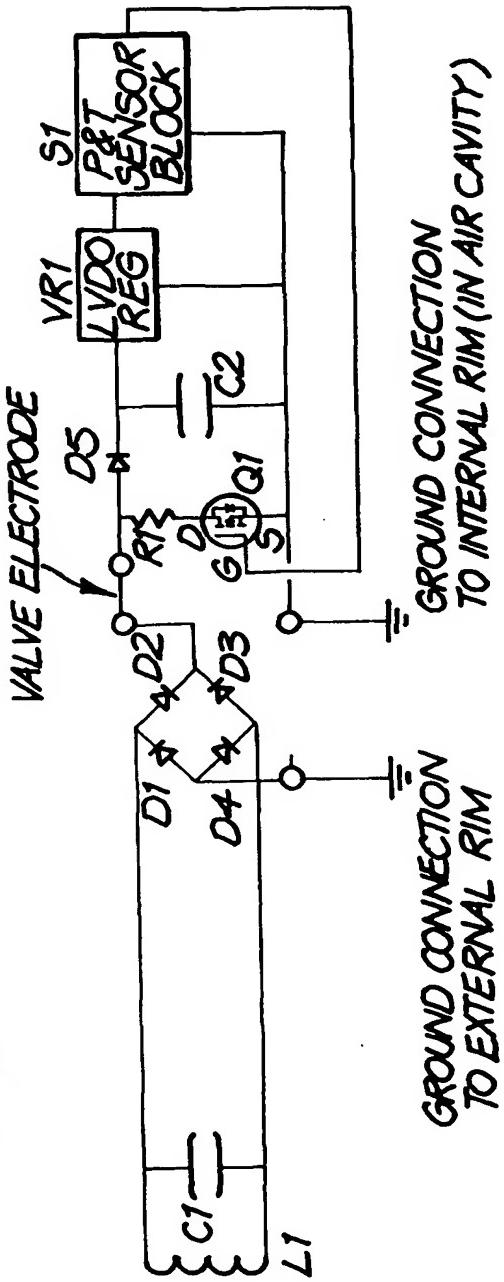
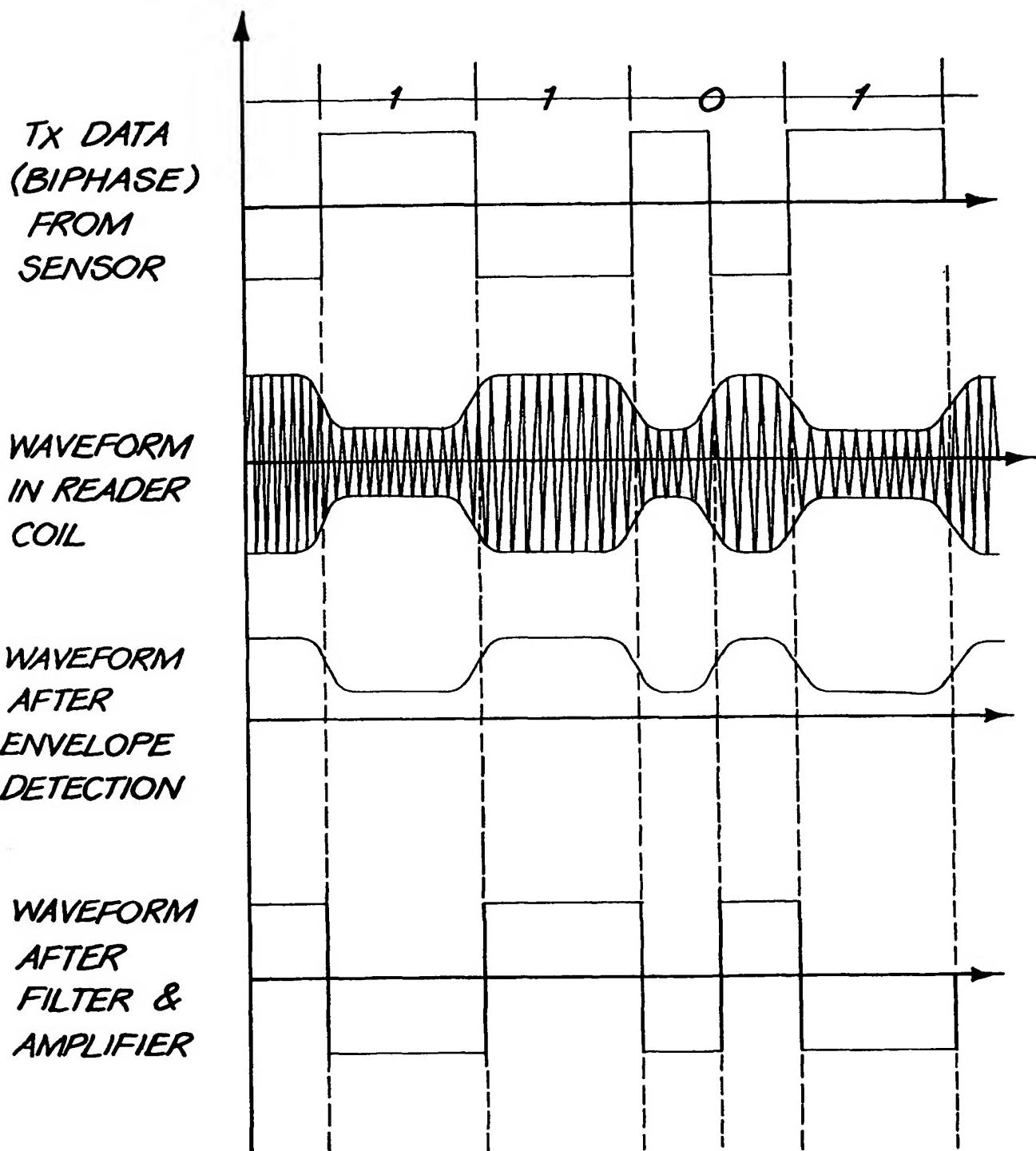


FIG. 15

ELECTROMAGNETIC COUPLING SIGNAL WAVEFORMS**FIG. 16**

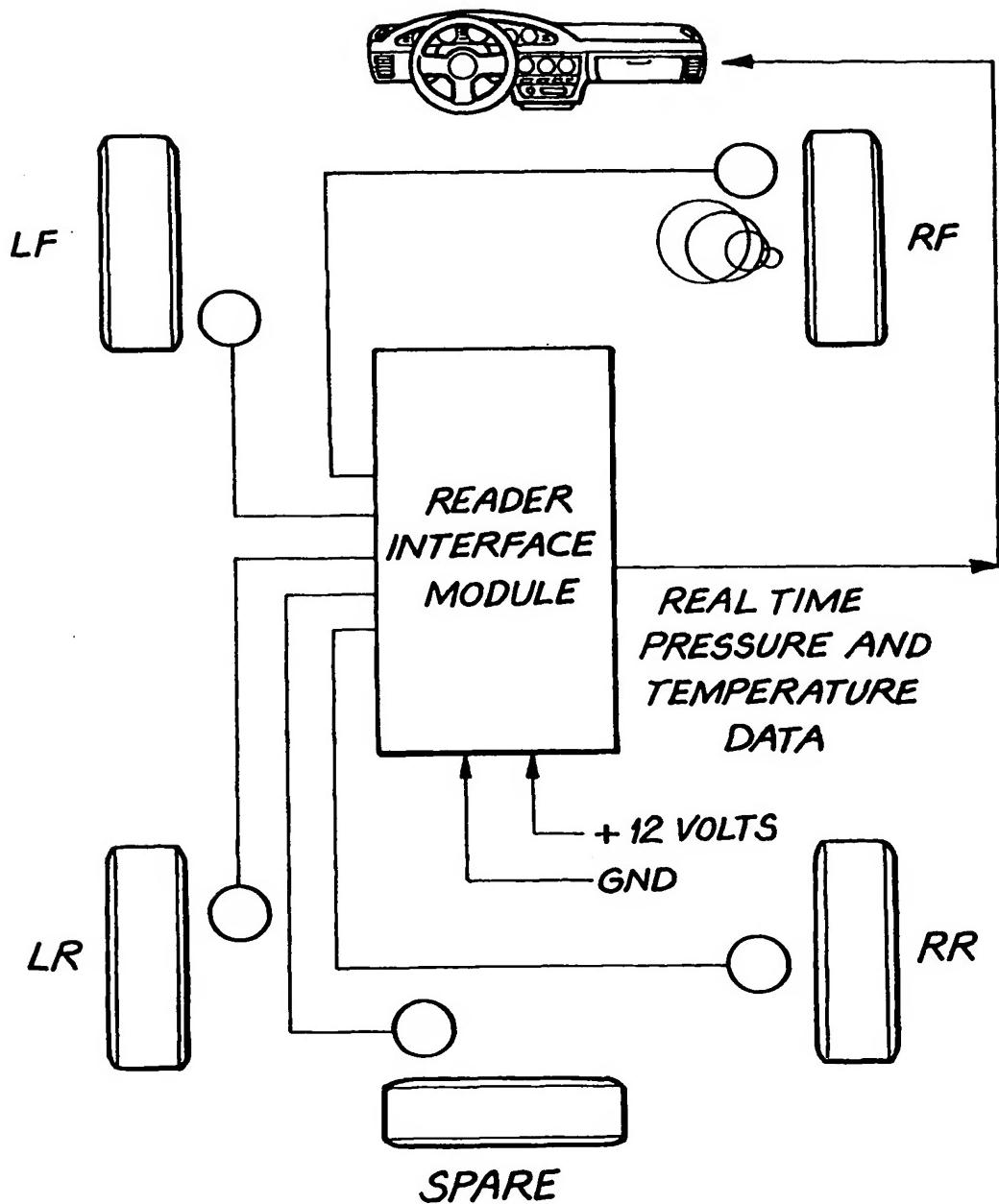


FIG. 17

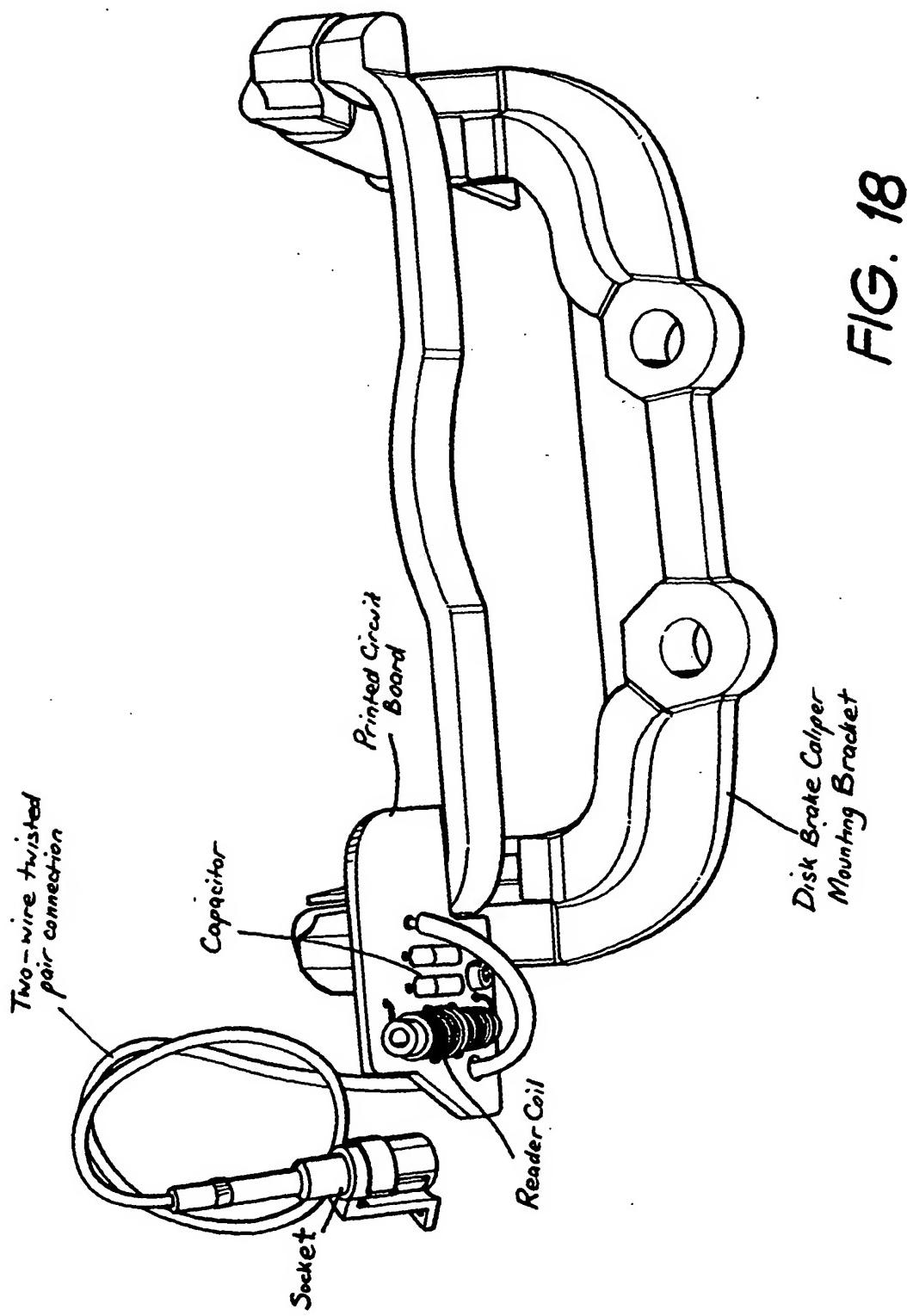


FIG. 18

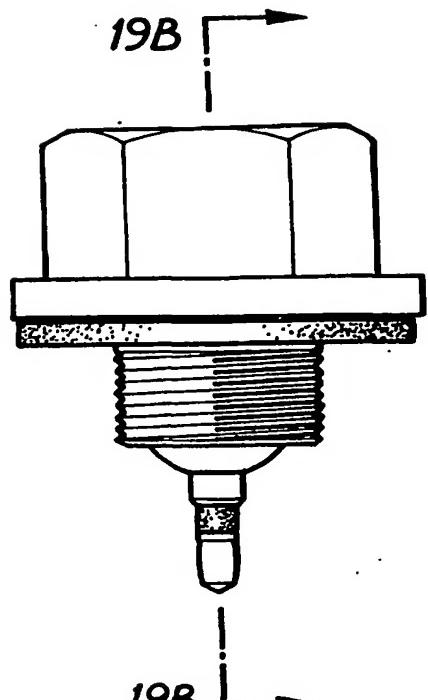


FIG. 19A

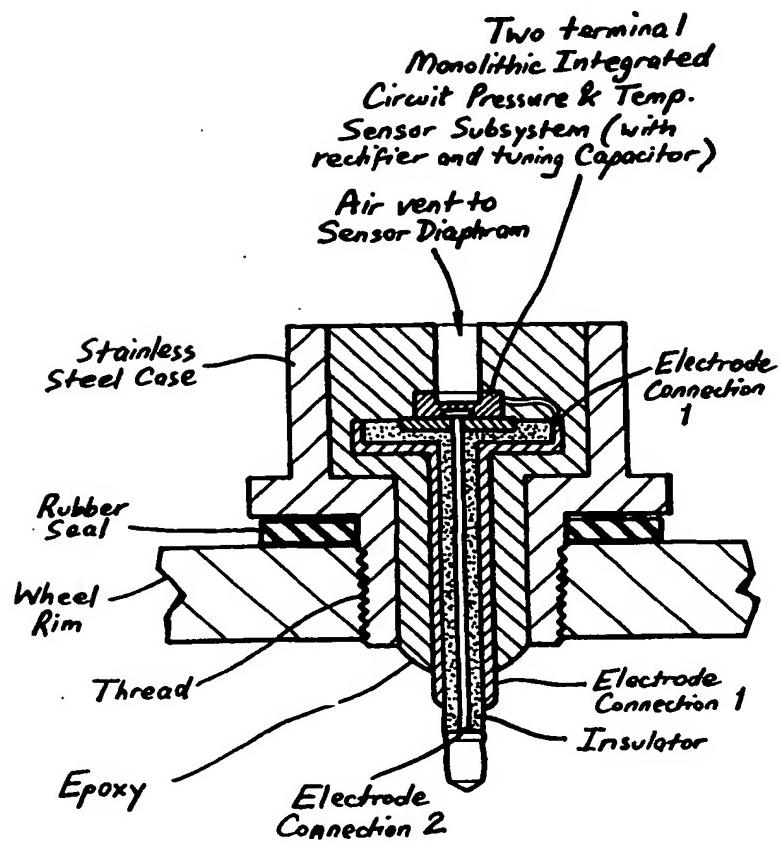


FIG. 19B

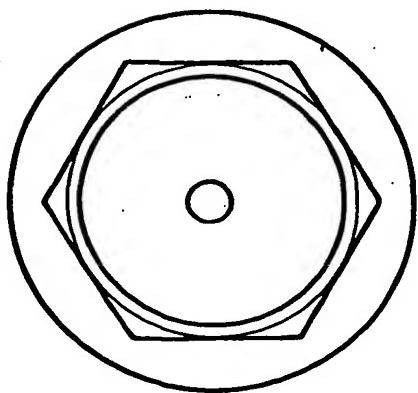


FIG. 19C

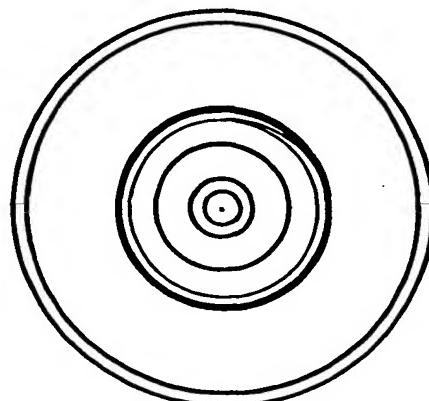


FIG. 19D